

# Chapter 20 - C++ Virtual Functions and Polymorphism

## Outline

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- 20.3 Virtual Functions**
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- 20.5 Polymorphism**
- 20.6 New Classes and Dynamic Binding**
- 20.7 Virtual Destructors**
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- 20.9 Polymorphism, virtual Functions and Dynamic Binding “Under the Hood”**



# Objectives

- In this chapter, you will learn:
  - To understand the notion of polymorphism.
  - To understand how to define and use `virtual` functions to effect polymorphism.
  - To understand the distinction between abstract classes and concrete classes.
  - To learn how to define pure `virtual` functions to create abstract classes.
  - To appreciate how polymorphism makes systems extensible and maintainable.
  - To understand how C++ implements `virtual` functions and dynamic binding “under the hood.”



## 20.1 Introduction

- virtual functions and polymorphism
  - Design and implement systems that are more easily extensible
  - Programs written to generically process objects of all existing classes in a hierarchy



## 20.2 Type Fields and switch Statements

- `switch` statement
  - Take an action on a object based on its type
  - A `switch` structure could determine which `print` function to call based on which type in a hierarchy of shapes
- Problems with `switch`
  - Programmer may forget to test all possible cases in a switch.
    - Tracking this down can be time consuming and error prone
    - `virtual` functions and polymorphic programming can eliminate the need for `switch`



## 20.3 Virtual Functions

- `virtual` functions
  - Used instead of `switch` statements
  - Definition:
    - Keyword `virtual` before function prototype in base class

```
virtual void draw() const;
```
  - A base-class pointer to a derived class object will call the correct `draw` function
  - If a derived class does not define a `virtual` function it is inherited from the base class



## 20.3 Virtual Functions

- `ShapePtr->Draw()` ;
  - Compiler implements dynamic binding
  - Function determined during execution time
  
- `ShapeObject.Draw()` ;
  - Compiler implements static binding
  - Function determined during compile-time



## 20.4 Abstract and Concrete Classes

- Abstract classes
  - Sole purpose is to provide a base class for other classes
  - No objects of an abstract base class can be instantiated
    - Too generic to define real objects, i.e. `TwoDimensionalShape`
    - Can have pointers and references
  - Concrete classes - classes that can instantiate objects
    - Provide specifics to make real objects, i.e. `Square`, `Circle`



## 20.4 Abstract and Concrete Classes

- Making abstract classes
  - Define one or more `virtual` functions as “pure” by initializing the function to zero

```
virtual double earnings() const = 0;
```

- Pure `virtual` function





## 20.5 Polymorphism

- Polymorphism:
  - Ability for objects of different classes to respond differently to the same function call
  - Base-class pointer (or reference) calls a `virtual` function
    - C++ chooses the correct overridden function in object
  - Suppose `print` not a `virtual` function

```
Employee e, *ePtr = &e;  
Hourlyworker h, *hPtr = &h;  
ePtr->print(); //call base-class print function  
hPtr->print(); //call derived-class print function  
ePtr=&h; //allowable implicit conversion  
ePtr->print(); // still calls base-class print
```



## 20.6 New Classes and Dynamic Binding

- Dynamic binding (late binding )
  - Object's type not needed when compiling virtual functions
  - Accommodate new classes that have been added after compilation
  - Important for ISV's (Independent Software Vendors) who do not wish to reveal source code to their customers



## 20.7 Virtual Destructors

- Problem:
  - If base-class pointer to a derived object is deleted, the base-class destructor will act on the object
- Solution:
  - Define a `virtual` base-class destructor
  - Now, the appropriate destructor will be called



## 20.8 Case Study: Inheriting Interface and Implementation

- Re-examine the Point, Circle, Cylinder hierarchy
  - Use the abstract base class Shape to head the hierarchy





## Outline



### 1. Shape Definition (abstract base class)

-----

### 1. Point Definition (derived class)

```
1 // Fig. 20.1: shape.h
2 // Definition of abstract base class Shape
3 #ifndef SHAPE_H
4 #define SHAPE_H
5
6 class Shape {
7 public:
8     virtual double area() const { return 0.0; }
9     virtual double volume() const { return 0.0; }
10
11     // pure virtual functions overridden in derived classes
12     virtual void printShapeName() const = 0;
13     virtual void print() const = 0;
14 }; // end class Shape
15
16 #endif
17 // Fig. 20.1: point1.h
18 // Definition of class Point
19 #ifndef POINT1_H
20 #define POINT1_H
21
22 #include <iostream>
23
24 using std::cout;
25
```



## Outline



### 1. Point Definition (derived class)

#### 1.1 Function Definitions

```
26 #include "shape.h"
27
28 class Point : public Shape {
29 public:
30     Point( int = 0, int = 0 ); // default constructor
31     void setPoint( int, int );
32     int getX() const { return x; }
33     int getY() const { return y; }
34     virtual void printShapeName() const { cout << "Point: "; }
35     virtual void print() const;
36 private:
37     int x, y; // x and y coordinates of Point
38 }; // end class Point
39
40 #endif
41 // Fig. 20.1: point1.cpp
42 // Member function definitions for class Point
43 #include "point1.h"
44
45 Point::Point( int a, int b ) { setPoint( a, b ); }
46
47 void Point::setPoint( int a, int b )
48 {
49     x = a;
50     y = b;
51 } // end function setPoint
52
```



## 1. Circle Definition (derived class)

```
53 void Point::print() const
54     { cout << '[' << x << ", " << y << ']' ; }
55 // Fig. 20.1: circle1.h
56 // Definition of class Circle
57 #ifndef CIRCLE1_H
58 #define CIRCLE1_H
59 #include "point1.h"
60
61 class Circle : public Point {
62 public:
63     // default constructor
64     circle( double r = 0.0, int x = 0, int y = 0 );
65
66     void setRadius( double );
67     double getRadius() const;
68     virtual double area() const;
69     virtual void printShapeName() const { cout << "Circle: "; }
70     virtual void print() const;
71 private:
72     double radius;    // radius of circle
73 }; // end class Circle
74
75 #endif
```



## 1.1 Function Definitions

```
76 // Fig. 20.1: circle1.cpp
77 // Member function definitions for class Circle
78 #include <iostream>
79
80 using std::cout;
81
82 #include "circle1.h"
83
84 Circle::Circle( double r, int a, int b )
85     : Point( a, b ) // call base-class constructor
86 { setRadius( r ); }
87
88 void Circle::setRadius( double r ) { radius = r > 0 ? r : 0; }
89
90 double Circle::getRadius() const { return radius; }
91
92 double Circle::area() const
93     { return 3.14159 * radius * radius; }
94
95 void Circle::print() const
96 {
97     Point::print();
98     cout << "; Radius = " << radius;
99 } // end function print
```





### 1. Cylinder Definition (derived class)

```
100 // Fig. 20.1: cylindr1.h
101 // Definition of class cylinder
102 #ifndef CYLINDR1_H
103 #define CYLINDR1_H
104 #include "circle1.h"
105
106 class cylinder : public Circle {
107 public:
108     // default constructor
109     cylinder( double h = 0.0, double r = 0.0,
110             int x = 0, int y = 0 );
111
112     void setHeight( double );
113     double getHeight();
114     virtual double area() const;
115     virtual double volume() const;
116     virtual void printShapeName() const { cout << "Cylinder: "; }
117     virtual void print() const;
118 private:
119     double height; // height of cylinder
120 }; // end class cylinder
121
122 #endif
```



### 1.1 Function Definitions

```
123 // Fig. 20.1: cylindr1.cpp
124 // Member and friend function definitions for class cylinder
125 #include <iostream>
126
127 using std::cout;
128
129 #include "cylindr1.h"
130
131 cylinder::cylinder( double h, double r, int x, int y )
132     : circle( r, x, y ) // call base-class constructor
133 { setHeight( h ); }
134
135 void cylinder::setHeight( double h )
136     { height = h > 0 ? h : 0; }
137
138 double cylinder::getHeight() { return height; }
139
140 double cylinder::area() const
141 {
142     // surface area of cylinder
143     return 2 * circle::area() +
144         2 * 3.14159 * getRadius() * height;
145 } // end function area
146
```



## Outline



### Driver

#### 1. Load headers

##### 1.1 Function prototypes

```
147 double cylinder::volume() const
148     { return circle::area() * height; }
149
150 void cylinder::print() const
151 {
152     circle::print();
153     cout << "; Height = " << height;
154 } // end function print
155 // Fig. 20.1: fig20_01.cpp
156 // Driver for shape, point, circle, cylinder hierarchy
157 #include <iostream>
158
159 using std::cout;
160 using std::endl;
161
162 #include <iomanip>
163
164 using std::ios;
165 using std::setiosflags;
166 using std::setprecision;
167
168 #include "shape.h"
169 #include "point1.h"
170 #include "circle1.h"
171 #include "cylindr1.h"
172
```



## 1.2 Initialize objects

## 2. Function calls

```
173 void virtualViaPointer( const Shape * );
174 void virtualViaReference( const Shape & );
175
176 int main()
177 {
178     cout << setiosflags( ios::fixed | ios::showpoint )
179         << setprecision( 2 );
180
181     Point point( 7, 11 );           // create a Point
182     Circle circle( 3.5, 22, 8 );   // create a Circle
183     Cylinder cylinder( 10, 3.3, 10, 10 ); // create a Cylinder
184
185     point.printShapeName();        // static binding
186     point.print();                // static binding
187     cout << '\n';
188
189     circle.printShapeName();       // static binding
190     circle.print();               // static binding
191     cout << '\n';
192
193     cylinder.printShapeName();     // static binding
194     cylinder.print();             // static binding
195     cout << "\n\n";
196
197     Shape *arrayOfShapes[ 3 ];    // array of base-class pointers
198
```



### 2. Function calls

```
199 // aim arrayOfShapes[0] at derived-class Point object
200 arrayOfShapes[ 0 ] = &point;
201
202 // aim arrayOfShapes[1] at derived-class Circle object
203 arrayOfShapes[ 1 ] = &circle;
204
205 // aim arrayOfShapes[2] at derived-class Cylinder object
206 arrayOfShapes[ 2 ] = &cylinder;
207
208 // Loop through arrayOfShapes and call virtualViaPointer
209 // to print the shape name, attributes, area, and volume
210 // of each object using dynamic binding.
211 cout << "virtual function calls made off "
212     << "base-class pointers\n";
213
214 for ( int i = 0; i < 3; i++ )
215     virtualViaPointer( arrayOfShapes[ i ] );
216
217 // Loop through arrayOfShapes and call virtualViaReference
218 // to print the shape name, attributes, area, and volume
219 // of each object using dynamic binding.
220 cout << "virtual function calls made off "
221     << "base-class references\n";
222
```



## 3. Function Definitions

```
223     for ( int j = 0; j < 3; j++ )
224         virtualViaReference( *arrayOfShapes[ j ] );
225
226     return 0;
227 } // end function main
228
229 // Make virtual function calls off a base-class pointer
230 // using dynamic binding.
231 void virtualViaPointer( const Shape *baseClassPtr )
232 {
233     baseClassPtr->printShapeName();
234     baseClassPtr->print();
235     cout << "\nArea = " << baseClassPtr->area()
236          << "\nVolume = " << baseClassPtr->volume() << "\n\n";
237 } // end function virtualViaPointer
238
239 // Make virtual function calls off a base-class reference
240 // using dynamic binding.
241 void virtualViaReference( const Shape &baseClassRef )
242 {
243     baseClassRef.printShapeName();
244     baseClassRef.print();
245     cout << "\nArea = " << baseClassRef.area()
246          << "\nVolume = " << baseClassRef.volume() << "\n\n";
247 } // end function virtualViaReference
```



## Program Output

```
Point: [7, 11]
Circle: [22, 8]; Radius = 3.50
Cylinder: [10, 10]; Radius = 3.30; Height = 10.00
```

Virtual function calls made off base-class pointers

```
Point: [7, 11]
Area = 0.00
Volume = 0.00
```

```
Circle: [22, 8]; Radius = 3.50
Area = 38.48
Volume = 0.00
```

```
Cylinder: [10, 10]; Radius = 3.30; Height = 10.00
Area = 275.77
Volume = 342.12
```

Virtual function calls made off base-class references

```
Point: [7, 11]
Area = 0.00
Volume = 0.00
```

```
Circle: [22, 8]; Radius = 3.50
Area = 38.48
Volume = 0.00
```

```
Cylinder: [10, 10]; Radius = 3.30; Height = 10.00
Area = 275.77
Volume = 342.12
```

## 20.9 Polymorphism, virtual Functions and Dynamic Binding “Under the Hood”

- When to use polymorphism
  - Polymorphism has a lot of overhead
- virtual function table (vtable)
  - Every class with a virtual function has a vtable
  - For every virtual function, vtable has a pointer to the proper function
    - If a derived class has the same function as a base class, then the function pointer points to the base-class function
  - Detailed explanation in Fig. 20.2

